

The following formulas might be useful for the solution of the exam problems:

FUNDAMENTAL CONSTANTS

ϵ_0	$= 8.85 \times 10^{-12} \text{ C}^2/\text{Nm}^2$	(permittivity of free space)
μ_0	$= 4\pi \times 10^{-7} \text{ N/A}^2$	(permeability of free space)
c	$= 3.00 \times 10^8 \text{ m/s}$	(speed of light)
e	$= 1.60 \times 10^{-19} \text{ C}$	(charge of the electron)
m	$= 9.11 \times 10^{-31} \text{ kg}$	(mass of the electron)

SPHERICAL AND CYLINDRICAL COORDINATES

Spherical

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases} \quad \begin{cases} \hat{\mathbf{x}} = \sin \theta \cos \phi \hat{\mathbf{r}} + \cos \theta \cos \phi \hat{\theta} - \sin \phi \hat{\phi} \\ \hat{\mathbf{y}} = \sin \theta \sin \phi \hat{\mathbf{r}} + \cos \theta \sin \phi \hat{\theta} + \cos \phi \hat{\phi} \\ \hat{\mathbf{z}} = \cos \theta \hat{\mathbf{r}} - \sin \theta \hat{\theta} \end{cases}$$

$$\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1}(\sqrt{x^2 + y^2}/z) \\ \phi = \tan^{-1}(y/x) \end{cases} \quad \begin{cases} \hat{\mathbf{r}} = \sin \theta \cos \phi \hat{\mathbf{x}} + \sin \theta \sin \phi \hat{\mathbf{y}} + \cos \theta \hat{\mathbf{z}} \\ \hat{\theta} = \cos \theta \cos \phi \hat{\mathbf{x}} + \cos \theta \sin \phi \hat{\mathbf{y}} - \sin \theta \hat{\mathbf{z}} \\ \hat{\phi} = -\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} \end{cases}$$

Cylindrical

$$\begin{cases} x = s \cos \phi \\ y = s \sin \phi \\ z = z \end{cases} \quad \begin{cases} \hat{\mathbf{x}} = \cos \phi \hat{\mathbf{s}} - \sin \phi \hat{\phi} \\ \hat{\mathbf{y}} = \sin \phi \hat{\mathbf{s}} + \cos \phi \hat{\phi} \\ \hat{\mathbf{z}} = \hat{\mathbf{z}} \end{cases}$$

$$\begin{cases} s = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1}(y/x) \\ z = z \end{cases} \quad \begin{cases} \hat{\mathbf{s}} = \cos \phi \hat{\mathbf{x}} + \sin \phi \hat{\mathbf{y}} \\ \hat{\phi} = -\sin \phi \hat{\mathbf{x}} + \cos \phi \hat{\mathbf{y}} \\ \hat{\mathbf{z}} = \hat{\mathbf{z}} \end{cases}$$

VECTOR IDENTITIES

TRIPLE PRODUCTS

$$(1) \quad \mathbf{A} \cdot (\mathbf{B} \times \mathbf{C}) = \mathbf{B} \cdot (\mathbf{C} \times \mathbf{A}) = \mathbf{C} \cdot (\mathbf{A} \times \mathbf{B})$$

$$(2) \quad \mathbf{A} \times (\mathbf{B} \times \mathbf{C}) = \mathbf{B}(\mathbf{A} \cdot \mathbf{C}) - \mathbf{C}(\mathbf{A} \cdot \mathbf{B})$$

PRODUCT RULES

$$(3) \quad \nabla(fg) = f(\nabla g) + g(\nabla f)$$

$$(4) \quad \nabla(\mathbf{A} \cdot \mathbf{B}) = \mathbf{A} \times (\nabla \times \mathbf{B}) + \mathbf{B} \times (\nabla \times \mathbf{A}) + (\mathbf{A} \cdot \nabla)\mathbf{B} + (\mathbf{B} \cdot \nabla)\mathbf{A}$$

$$(5) \quad \nabla \cdot (f\mathbf{A}) = f(\nabla \cdot \mathbf{A}) + \mathbf{A} \cdot (\nabla f)$$

$$(6) \quad \nabla \cdot (\mathbf{A} \times \mathbf{B}) = \mathbf{B} \cdot (\nabla \times \mathbf{A}) - \mathbf{A} \cdot (\nabla \times \mathbf{B})$$

$$(7) \quad \nabla \times (f\mathbf{A}) = f(\nabla \times \mathbf{A}) - \mathbf{A} \times (\nabla f)$$

$$(8) \quad \nabla \times (\mathbf{A} \times \mathbf{B}) = (\mathbf{B} \cdot \nabla)\mathbf{A} - (\mathbf{A} \cdot \nabla)\mathbf{B} + \mathbf{A}(\nabla \cdot \mathbf{B}) - \mathbf{B}(\nabla \cdot \mathbf{A})$$

SECOND DERIVATIVES

$$(9) \quad \nabla \cdot (\nabla \times \mathbf{A}) = 0$$

$$(10) \quad \nabla \times (\nabla f) = 0$$

$$(11) \quad \nabla \times (\nabla \times \mathbf{A}) = \nabla(\nabla \cdot \mathbf{A}) - \nabla^2 \mathbf{A}$$

FUNDAMENTAL THEOREMS

Gradient Theorem:
$$\int_a^b (\nabla f) \cdot d\mathbf{l} = f(b) - f(a)$$

Divergence Theorem:
$$\int_{\text{volume}} (\nabla \cdot \mathbf{A}) d\tau = \oint_{\text{surface}} \mathbf{A} \cdot d\mathbf{a}$$

Curl Theorem:
$$\int_{\text{surface}} (\nabla \times \mathbf{A}) \cdot d\mathbf{a} = \oint_{\text{line}} \mathbf{A} \cdot d\mathbf{l}$$

VECTOR DERIVATIVES

Cartesian. $d\mathbf{l} = dx \hat{\mathbf{x}} + dy \hat{\mathbf{y}} + dz \hat{\mathbf{z}}; \quad d\tau = dx dy dz$

Gradient : $\nabla t = \frac{\partial t}{\partial x} \hat{\mathbf{x}} + \frac{\partial t}{\partial y} \hat{\mathbf{y}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

Divergence : $\nabla \cdot \mathbf{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$

Curl : $\nabla \times \mathbf{v} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \hat{\mathbf{x}} + \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \hat{\mathbf{y}} + \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \hat{\mathbf{z}}$

Laplacian : $\nabla^2 t = \frac{\partial^2 t}{\partial x^2} + \frac{\partial^2 t}{\partial y^2} + \frac{\partial^2 t}{\partial z^2}$

Spherical. $d\mathbf{l} = dr \hat{\mathbf{r}} + r d\theta \hat{\boldsymbol{\theta}} + r \sin \theta d\phi \hat{\boldsymbol{\phi}}; \quad d\tau = r^2 \sin \theta dr d\theta d\phi = r^2 dr d\cos \theta d\phi$

Gradient : $\nabla t = \frac{\partial t}{\partial r} \hat{\mathbf{r}} + \frac{1}{r} \frac{\partial t}{\partial \theta} \hat{\boldsymbol{\theta}} + \frac{1}{r \sin \theta} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}}$

Divergence : $\nabla \cdot \mathbf{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$

Curl : $\nabla \times \mathbf{v} = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (\sin \theta v_\phi) - \frac{\partial v_\theta}{\partial \phi} \right] \hat{\mathbf{r}}$
 $+ \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{\partial}{\partial r} (r v_\phi) \right] \hat{\boldsymbol{\theta}} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r v_\theta) - \frac{\partial v_r}{\partial \theta} \right] \hat{\boldsymbol{\phi}}$

Laplacian : $\nabla^2 t = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial t}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial t}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 t}{\partial \phi^2}$

Cylindrical. $d\mathbf{l} = ds \hat{\mathbf{s}} + s d\phi \hat{\boldsymbol{\phi}} + dz \hat{\mathbf{z}}; \quad d\tau = s ds d\phi dz$

Gradient : $\nabla t = \frac{\partial t}{\partial s} \hat{\mathbf{s}} + \frac{1}{s} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

Divergence : $\nabla \cdot \mathbf{v} = \frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$

Curl : $\nabla \times \mathbf{v} = \left[\frac{1}{s} \frac{\partial v_z}{\partial \phi} - \frac{\partial v_\phi}{\partial z} \right] \hat{\mathbf{s}} + \left[\frac{\partial v_s}{\partial z} - \frac{\partial v_z}{\partial s} \right] \hat{\boldsymbol{\phi}} + \frac{1}{s} \left[\frac{\partial}{\partial s} (s v_\phi) - \frac{\partial v_s}{\partial \phi} \right] \hat{\mathbf{z}}$

Laplacian : $\nabla^2 t = \frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial t}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 t}{\partial \phi^2} + \frac{\partial^2 t}{\partial z^2}$

Maxwell's Equations

Translation of equations in SI system to those using Gauß system:

$$q, \rho, I, \dots \text{ [Gauß]} = \frac{1}{\sqrt{4\pi\epsilon_0}} q, \rho, I, \dots \text{ [SI]}$$

$$\vec{E} \text{ [Gauß]} = \sqrt{4\pi\epsilon_0} \vec{E} \text{ [SI]}; \quad \vec{B} \text{ [Gauß]} = \sqrt{4\pi\epsilon_0} c \vec{B} \text{ [SI]}$$

Maxwell's Equations in free space:

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \text{ [SI]}, \quad \vec{\nabla} \cdot \vec{E} = 4\pi\rho \text{ [Gauß]}; \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \text{ [SI]}, \quad \vec{\nabla} \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t} \text{ [Gauß]}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad ; \quad \vec{\nabla} \times \vec{B} = \mu_0 \left(\vec{j} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) \text{ [SI]}, \quad \vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \text{ [Gauß]}$$

Lorentz Force Law: $\vec{F} = Q(\vec{E} + \vec{v} \times \vec{B})$ [SI], $\vec{F} = Q\left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B}\right)$ [Gauß];

Continuity Equation: $\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{J} = 0$

AUXILLARY FIELDS

Definitions:

$$\begin{cases} \mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P} \\ \mathbf{H} = \frac{1}{\mu_0} \mathbf{B} - \mathbf{M} \end{cases}$$

In linear media:

$$\begin{cases} \mathbf{P} = \epsilon_0 \chi_e \mathbf{E}, & \mathbf{D} = \epsilon \mathbf{E} \\ \mathbf{M} = \chi_m \mathbf{H}, & \mathbf{H} = \frac{1}{\mu} \mathbf{B} \end{cases}$$

Potential Formulation of Maxwell's Equations [SI]

$$\vec{E} = -\vec{\nabla}V - \dot{\vec{A}} \quad \vec{B} = \vec{\nabla} \times \vec{A}$$

Coulomb Gauge: $\vec{\nabla} \cdot \vec{A} = 0 \Rightarrow$

$$\vec{\nabla}^2 V = -\frac{\rho}{\epsilon_0}; \quad \square \vec{A} = \mu_0 \vec{J} - \frac{1}{c^2} \frac{\partial}{\partial t} \vec{\nabla} V \quad \text{where}$$

$$\square = \frac{1}{c^2} \frac{\partial^2}{\partial t^2} - \vec{\nabla}^2 = \epsilon_0 \mu_0 \frac{\partial^2}{\partial t^2} - \vec{\nabla}^2$$

Lorentz Gauge: $\frac{1}{c^2} \frac{\partial}{\partial t} V + \vec{\nabla} \cdot \vec{A} = 0 \Rightarrow$

$$\square V = \frac{\rho}{\epsilon_0}; \quad \square \vec{A} = \mu_0 \vec{J}$$

Lorentz Force Law: $\frac{d}{dt} (\vec{p} + q\vec{A}) = q \vec{\nabla} [\vec{v} \cdot \vec{A}(\vec{r}) - V(\vec{r})]$

ENERGY, MOMENTUM, AND POWER

Energy:
$$W = \frac{1}{2} \int \left(\epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right) d\tau$$

Momentum:
$$\mathbf{P} = \epsilon_0 \int (\mathbf{E} \times \mathbf{B}) d\tau$$

Poynting vector:
$$\mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \times \mathbf{B})$$

Larmor formula:
$$P = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2 a^2}{c^3}$$

The Dirac Delta Function:

In one dimension:
$$\delta(x - x') = \begin{cases} 0 & \text{for } x \neq x' \\ \infty & \text{for } x = x' \end{cases}$$

$$\int_a^b f(x) \delta(x - x_0) dx = \begin{cases} 0 & \text{for } x_0 \notin [a, b] \\ f(x_0) & \text{for } x_0 \in [a, b] \end{cases}$$

In three dimensions:
$$\delta^3(\vec{r} - \vec{r}_0) = \delta(x) \delta(y) \delta(z)$$

For some smooth scalar field $f(\mathbf{r})$:
$$\iiint_{\text{Volume}} f(\vec{r}') \delta^3(\vec{r} - \vec{r}') d^3r' = f(\vec{r}) \text{ if } \vec{r} \in \text{Volume}$$

If $f(x)$ is a strictly monotonous function with one zero x_0 ($f(x_0) = 0$), then

$$\delta(f(x)) = \frac{1}{f'(x_0)} \cdot \delta(x - x_0)$$

Divergence of Coulomb field:
$$\vec{\nabla}_r \cdot \frac{\vec{r} - \vec{r}'}{|\vec{r} - \vec{r}'|^3} = -\vec{\nabla}_r^2 \frac{1}{|\vec{r} - \vec{r}'|} = 4\pi\delta^3(\vec{r} - \vec{r}')$$
