

The following formulas might be useful:

FUNDAMENTAL CONSTANTS

ϵ_0	$= 8.85 \times 10^{-12} \text{ C}^2/\text{Nm}^2$	(permittivity of free space)
μ_0	$= 4\pi \times 10^{-7} \text{ N/A}^2$	(permeability of free space)
c	$= 3.00 \times 10^8 \text{ m/s}$	(speed of light)
e	$= 1.60 \times 10^{-19} \text{ C}$	(charge of the electron)
m	$= 9.11 \times 10^{-31} \text{ kg}$	(mass of the electron)

SPHERICAL AND CYLINDRICAL COORDINATES

Spherical

$$\begin{cases} x = r \sin \theta \cos \phi \\ y = r \sin \theta \sin \phi \\ z = r \cos \theta \end{cases} \quad \begin{cases} \hat{x} = \sin \theta \cos \phi \hat{r} + \cos \theta \cos \phi \hat{\theta} - \sin \phi \hat{\phi} \\ \hat{y} = \sin \theta \sin \phi \hat{r} + \cos \theta \sin \phi \hat{\theta} + \cos \phi \hat{\phi} \\ \hat{z} = \cos \theta \hat{r} - \sin \theta \hat{\theta} \end{cases}$$

$$\begin{cases} r = \sqrt{x^2 + y^2 + z^2} \\ \theta = \tan^{-1}(\sqrt{x^2 + y^2}/z) \\ \phi = \tan^{-1}(y/x) \end{cases} \quad \begin{cases} \hat{r} = \sin \theta \cos \phi \hat{x} + \sin \theta \sin \phi \hat{y} + \cos \theta \hat{z} \\ \hat{\theta} = \cos \theta \cos \phi \hat{x} + \cos \theta \sin \phi \hat{y} - \sin \theta \hat{z} \\ \hat{\phi} = -\sin \phi \hat{x} + \cos \phi \hat{y} \end{cases}$$

Cylindrical

$$\begin{cases} x = s \cos \phi \\ y = s \sin \phi \\ z = z \end{cases} \quad \begin{cases} \hat{x} = \cos \phi \hat{s} - \sin \phi \hat{\phi} \\ \hat{y} = \sin \phi \hat{s} + \cos \phi \hat{\phi} \\ \hat{z} = \hat{z} \end{cases}$$

$$\begin{cases} s = \sqrt{x^2 + y^2} \\ \phi = \tan^{-1}(y/x) \\ z = z \end{cases} \quad \begin{cases} \hat{s} = \cos \phi \hat{x} + \sin \phi \hat{y} \\ \hat{\phi} = -\sin \phi \hat{x} + \cos \phi \hat{y} \\ \hat{z} = \hat{z} \end{cases}$$

VECTOR DERIVATIVES

Cartesian. $d\mathbf{l} = dx \hat{\mathbf{x}} + dy \hat{\mathbf{y}} + dz \hat{\mathbf{z}}; \quad d\tau = dx dy dz$

Gradient : $\nabla t = \frac{\partial t}{\partial x} \hat{\mathbf{x}} + \frac{\partial t}{\partial y} \hat{\mathbf{y}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

Divergence : $\nabla \cdot \mathbf{v} = \frac{\partial v_x}{\partial x} + \frac{\partial v_y}{\partial y} + \frac{\partial v_z}{\partial z}$

Curl : $\nabla \times \mathbf{v} = \left(\frac{\partial v_z}{\partial y} - \frac{\partial v_y}{\partial z} \right) \hat{\mathbf{x}} + \left(\frac{\partial v_x}{\partial z} - \frac{\partial v_z}{\partial x} \right) \hat{\mathbf{y}} + \left(\frac{\partial v_y}{\partial x} - \frac{\partial v_x}{\partial y} \right) \hat{\mathbf{z}}$

Laplacian : $\nabla^2 t = \frac{\partial^2 t}{\partial x^2} + \frac{\partial^2 t}{\partial y^2} + \frac{\partial^2 t}{\partial z^2}$

Spherical. $d\mathbf{l} = dr \hat{\mathbf{r}} + r d\theta \hat{\boldsymbol{\theta}} + r \sin \theta d\phi \hat{\boldsymbol{\phi}}; \quad d\tau = r^2 \sin \theta dr d\theta d\phi = r^2 dr d\cos \theta d\phi$

Gradient : $\nabla t = \frac{\partial t}{\partial r} \hat{\mathbf{r}} + \frac{1}{r} \frac{\partial t}{\partial \theta} \hat{\boldsymbol{\theta}} + \frac{1}{r \sin \theta} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}}$

Divergence : $\nabla \cdot \mathbf{v} = \frac{1}{r^2} \frac{\partial}{\partial r} (r^2 v_r) + \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta v_\theta) + \frac{1}{r \sin \theta} \frac{\partial v_\phi}{\partial \phi}$

Curl : $\nabla \times \mathbf{v} = \frac{1}{r \sin \theta} \left[\frac{\partial}{\partial \theta} (\sin \theta v_\phi) - \frac{\partial v_\theta}{\partial \phi} \right] \hat{\mathbf{r}}$
 $+ \frac{1}{r} \left[\frac{1}{\sin \theta} \frac{\partial v_r}{\partial \phi} - \frac{\partial}{\partial r} (r v_\phi) \right] \hat{\boldsymbol{\theta}} + \frac{1}{r} \left[\frac{\partial}{\partial r} (r v_\theta) - \frac{\partial v_r}{\partial \theta} \right] \hat{\boldsymbol{\phi}}$

Laplacian : $\nabla^2 t = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial t}{\partial r} \right) + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial t}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 t}{\partial \phi^2}$

Cylindrical. $d\mathbf{l} = ds \hat{\mathbf{s}} + s d\phi \hat{\boldsymbol{\phi}} + dz \hat{\mathbf{z}}; \quad d\tau = s ds d\phi dz$

Gradient : $\nabla t = \frac{\partial t}{\partial s} \hat{\mathbf{s}} + \frac{1}{s} \frac{\partial t}{\partial \phi} \hat{\boldsymbol{\phi}} + \frac{\partial t}{\partial z} \hat{\mathbf{z}}$

Divergence : $\nabla \cdot \mathbf{v} = \frac{1}{s} \frac{\partial}{\partial s} (s v_s) + \frac{1}{s} \frac{\partial v_\phi}{\partial \phi} + \frac{\partial v_z}{\partial z}$

Curl : $\nabla \times \mathbf{v} = \left[\frac{1}{s} \frac{\partial v_z}{\partial \phi} - \frac{\partial v_\phi}{\partial z} \right] \hat{\mathbf{s}} + \left[\frac{\partial v_s}{\partial z} - \frac{\partial v_z}{\partial s} \right] \hat{\boldsymbol{\phi}} + \frac{1}{s} \left[\frac{\partial}{\partial s} (s v_\phi) - \frac{\partial v_s}{\partial \phi} \right] \hat{\mathbf{z}}$

Laplacian : $\nabla^2 t = \frac{1}{s} \frac{\partial}{\partial s} \left(s \frac{\partial t}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 t}{\partial \phi^2} + \frac{\partial^2 t}{\partial z^2}$

The Dirac Delta Function:

In one dimension: $\delta(x - x') = \begin{cases} 0 & \text{for } x \neq x' \\ \infty & \text{for } x = x' \end{cases}$

$$\int_a^b f(x) \delta(x - x_o) dx = \begin{cases} 0 & \text{for } x_o \notin [a, b] \\ f(x_o) & \text{for } x_o \in [a, b] \end{cases}$$

Maxwell's Equations

Translation of equations in SI system to those using Gauß system:

$$q, \rho, I, \dots \text{ [Gauß]} = \frac{1}{\sqrt{4\pi\epsilon_0}} q, \rho, I, \dots \text{ [SI]}$$

$$\vec{E} \text{ [Gauß]} = \sqrt{4\pi\epsilon_0} \vec{E} \text{ [SI]}; \quad \vec{B} \text{ [Gauß]} = \sqrt{4\pi\epsilon_0} c \vec{B} \text{ [SI]}$$

Maxwell's Equations in free space:

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \text{ [SI]}, \quad \vec{\nabla} \cdot \vec{E} = 4\pi\rho \text{ [Gauß]}; \quad \vec{\nabla} \times \vec{E} = -\frac{\partial \vec{B}}{\partial t} \text{ [SI]}, \quad \vec{\nabla} \times \vec{E} = -\frac{1}{c} \frac{\partial \vec{B}}{\partial t} \text{ [Gauß]}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad ; \quad \vec{\nabla} \times \vec{B} = \mu_0 \left(\vec{j} + \epsilon_0 \frac{\partial \vec{E}}{\partial t} \right) \text{ [SI]}, \quad \vec{\nabla} \times \vec{B} = \frac{4\pi}{c} \vec{j} + \frac{1}{c} \frac{\partial \vec{E}}{\partial t} \text{ [Gauß]}$$

Lorentz Force Law: $\vec{F} = Q(\vec{E} + \vec{v} \times \vec{B}) \text{ [SI]}, \quad \vec{F} = Q\left(\vec{E} + \frac{\vec{v}}{c} \times \vec{B}\right) \text{ [Gauß]};$

Continuity Equation: $\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{J} = 0$

AUXILLARY FIELDS

Definitions:

$$\begin{cases} \mathbf{D} = \epsilon_0 \mathbf{E} + \mathbf{P} \\ \mathbf{H} = \frac{1}{\mu_0} \mathbf{B} - \mathbf{M} \end{cases}$$

In linear media:

$$\begin{cases} \mathbf{P} = \epsilon_0 \chi_e \mathbf{E}, & \mathbf{D} = \epsilon \mathbf{E} \\ \mathbf{M} = \chi_m \mathbf{H}, & \mathbf{H} = \frac{1}{\mu} \mathbf{B} \end{cases}$$

P = polarization of medium = density of electric dipole moments

M = magnetization of medium = density of magnetic dipole moments

PHYSICS - ODU

ENERGY, MOMENTUM, AND POWER

$$\text{Energy:} \quad W = \frac{1}{2} \int \left(\epsilon_0 E^2 + \frac{1}{\mu_0} B^2 \right) d\tau$$

$$\text{Momentum:} \quad \mathbf{P} = \epsilon_0 \int (\mathbf{E} \times \mathbf{B}) d\tau$$

$$\text{Poynting vector:} \quad \mathbf{S} = \frac{1}{\mu_0} (\mathbf{E} \times \mathbf{B})$$

$$\text{Larmor formula:} \quad P = \frac{1}{4\pi\epsilon_0} \frac{2}{3} \frac{q^2 a^2}{c^3}$$

Electrostatics (NO moving charges)

Coulomb's law (Fundamental Form – single point charge q at position \vec{r}_q):

$$\vec{E}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{\vec{r} - \vec{r}_q}{|\vec{r} - \vec{r}_q|^3}$$

Gauss' law (integral version):

$$\oiint_{\text{Closed Surface}} \vec{E} \cdot d\vec{a} = \frac{1}{\epsilon_0} Q_{\text{enclosed}}$$

Field of a spherically symmetric charge distribution in free space:

$$\vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{Q(\text{encl within radius } r)}{r^2} \hat{r}$$

Field of a cylindrically symmetric charge distribution in free space:

$$\vec{E}(\vec{r}) = \frac{1}{2\pi\epsilon_0} \frac{Q/L(\text{encl within radius } s)}{s} \hat{s}$$

Electric potential:

$$V(\vec{r}) = - \int_{\text{Some path from } \vec{r}_0}^{\vec{r}} \vec{E}(\vec{r}') \cdot d\vec{l}(r') \quad ; \quad \vec{E}(\vec{r}) = -\vec{\nabla}V(\vec{r}) \quad ; \quad \mathbf{r}_0 \text{ is the reference point where } V = 0.$$

PHYSICS - ODU

Potential of a single point charge q at position \vec{r}_q :

$$V(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{1}{|\vec{r} - \vec{r}_q|}$$

Work done on a charge Q moved from point \mathbf{r}_1 to \mathbf{r}_2 :

$$W = Q (V(\mathbf{r}_2) - V(\mathbf{r}_1))$$

Potential energy: $U_{\text{pot}}(Q \text{ at } \mathbf{r}) = Q \cdot V(\mathbf{r})$

Energy of a point charge distribution:

$$W = \frac{1}{2} \cdot \sum_{i=1}^n q_i \left[\sum_{j \neq i} \frac{1}{4\pi\epsilon_0} \frac{q_j}{|\vec{r}_i - \vec{r}_j|} \right]$$

Electric Dipole moment

$$m_1(\hat{r}) = \iiint \rho(\vec{r}') r' (\hat{r}' \cdot \hat{r}) d^3 r' = \hat{r} \cdot \vec{p}; \quad \vec{p} = \iiint \vec{r}' \rho(\vec{r}') d^3 r'$$

Potential of a (pure) dipole:

$$V(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{1}{r^2} \hat{r} \cdot \vec{p}; \quad \text{field: } \vec{E}(\vec{r}) = \frac{1}{4\pi\epsilon_0} \frac{1}{r^3} \left[3(\vec{p} \cdot \hat{r}) \hat{r} - \vec{p} \right]$$

In spherical coordinates (dipole pointing along z-axis):

$$V(r, \theta, \varphi) = \frac{p \cos \theta}{4\pi\epsilon_0 r^2}; \quad \text{field: } \vec{E}(r, \theta, \varphi) = \frac{1}{4\pi\epsilon_0} \frac{p}{r^3} \left[2 \cos \theta \hat{r} + \sin \theta \hat{\theta} \right]$$

Force on a dipole: $\vec{F} = (\vec{p} \cdot \vec{\nabla}) \vec{E}$; Torque: $\vec{N} = \vec{p} \times \vec{E}$.

Energy of a dipole in an electric field: $W = -\vec{p} \cdot \vec{E}$

Magnetostatics

Cyclotron motion

$|p_{\text{perp}}| = |QBR|$ (momentum perpendicular to the magnetic field B for a particle with charge Q , orbiting on a circular or helical trajectory with radius R);

$\omega = \frac{|QB|}{m}$ (angular velocity of a particle with charge Q , mass m in a field B).

Work on moving charges done by magnetic forces: None.

PHYSICS - ODU

Current densities produced by some charge distribution, moving with velocity \mathbf{v} :

Volume current density: $\mathbf{J} = \rho \mathbf{v}$. Force on this current: $\mathbf{F} = \iiint \mathbf{J}(\mathbf{r}') \times \mathbf{B}(\mathbf{r}') d^3r'$

Surface current density: $\mathbf{K} = \sigma \mathbf{v}$. Force on this current: $\mathbf{F} = \iint \mathbf{K}(\mathbf{r}') \times \mathbf{B}(\mathbf{r}') da(r')$

(take *average* of \mathbf{B}).

Line current: $\mathbf{I} = \lambda \mathbf{v}$. Force on this current: $\mathbf{F} = \int \mathbf{I}(\mathbf{r}') \times \mathbf{B}(\mathbf{r}') d\ell(r')$.

Total current flowing through some area A : Volume current density $\Rightarrow I = \iint \mathbf{J} \cdot d\mathbf{a}$

Surface current density $\Rightarrow I = \int K_{\text{perp}} dl$.

(= Line integral along the intersection of the area A and the surface on which \mathbf{K} is confined, of the component of \mathbf{K} perpendicular to that line)

Continuity equation for Magneto- and Electrostatics: $\vec{\nabla} \cdot \vec{\mathbf{J}} = -\frac{\partial \rho}{\partial t} = 0$.

Biot-Savart law for a steady volume current density:

$$\vec{\mathbf{B}}(\vec{\mathbf{r}}) = \frac{\mu_0}{4\pi} \iiint_{\text{All Space}} \vec{\mathbf{J}}(\vec{\mathbf{r}}') \times \frac{\vec{\mathbf{r}} - \vec{\mathbf{r}}'}{|\vec{\mathbf{r}} - \vec{\mathbf{r}}'|^3} d^3r'$$

For the two other kinds of current distributions, the integral goes over a surface or a path.

Ampere's law in integral form

$$\oint \vec{\mathbf{B}} \cdot d\vec{\ell} = \mu_0 I_{\text{encl}}, \text{ where } I_{\text{encl}} \text{ is the current going through any surface spanned}$$

Closed Loop

by the loop, in the direction of the normal on that surface (which is related to the direction of the path around the loop via the right-hand rule).

Magnetic Dipole

The field is $\vec{\mathbf{B}}_{\text{dipole}}(\vec{\mathbf{r}}) = \frac{\mu_0}{4\pi} \frac{1}{r^3} [3(\vec{\mathbf{m}} \cdot \hat{\mathbf{r}})\hat{\mathbf{r}} - \vec{\mathbf{m}}]$. For a flat wire loop surrounding area a

with current I , the dipole moment is $\vec{\mathbf{m}} = Ia\hat{\mathbf{n}}$ ($\hat{\mathbf{n}}$ is the normal on the area).

Torque and force on a magnetic dipole: $\vec{\mathbf{N}} = \vec{\mathbf{m}} \times \vec{\mathbf{B}}$; $\vec{\mathbf{F}} = (\vec{\mathbf{m}} \cdot \vec{\nabla}) \vec{\mathbf{B}}$

Electromagnetic waves

Prototype – plane wave:

$$\vec{E}(\vec{r}, t) = \vec{E}_0 \cos(\vec{k} \cdot \vec{r} - \omega t); \quad \vec{B}(\vec{r}, t) = \vec{B}_0 \cos(\vec{k} \cdot \vec{r} - \omega t)$$

with

$$k = \frac{2\pi}{\lambda}; \quad \omega = 2\pi f = \frac{2\pi}{T} = k \cdot v_{\text{phase}} = k \cdot c / n$$

$$\vec{E}_0 \perp \hat{k}; \quad \vec{B}_0 = \frac{\hat{k}}{v_{\text{phase}}} \times \vec{E}_0 = \frac{\vec{k}}{\omega} \times \vec{E}_0$$

where λ is the wave length, f is the frequency, \vec{k} is the wave vector, v_{phase} is the phase velocity (which is equal to $c = 3 \cdot 10^8$ m/s in vacuum and equal to c/n in a medium with refractive index n).

Complex form: $\vec{E}(\vec{r}, t) = \text{Re}\{\vec{E}_c(\vec{r}, t)\}; \quad \vec{E}_c(\vec{r}, t) = \vec{E}_0 e^{i(\vec{k} \cdot \vec{r} - \omega t)}$

Energy density (energy per unit volume, J/m³):

$$\frac{\Delta E}{\Delta \text{Vol}} = \frac{\epsilon_0}{2} \vec{E}^2(\vec{r}, t) + \frac{1}{2\mu_0} \vec{B}^2(\vec{r}, t) = \epsilon_0 \vec{E}_0^2 \cos^2(\vec{k} \cdot \vec{r} - \omega t) \Rightarrow \left\langle \frac{\Delta E}{\Delta \text{Vol}} \right\rangle = \frac{\epsilon_0}{2} \vec{E}_0^2 \text{ (average)}$$

Average energy current density (Intensity, “brightness”; W/m²):

$$\frac{\Delta E}{\Delta \text{Area} \Delta t} = c \frac{\Delta E}{\Delta \text{Vol}} = \frac{c\epsilon_0}{2} \vec{E}_0^2 = \frac{1}{2\mu_0 c} \vec{E}_0^2 = \left\langle \vec{S} \right\rangle$$

with the Poynting vector

$$\vec{S} = \frac{1}{\mu_0} \vec{E}(\vec{r}, t) \times \vec{B}(\vec{r}, t) = \frac{\hat{k}}{\mu_0 c} \vec{E}_0^2 \cos^2(\vec{k} \cdot \vec{r} - \omega t)$$

Momentum flux density (amount of momentum in \vec{k} –direction carried through a unit surface perpendicular to \vec{k} per unit time):

$$\langle S \rangle / c = \frac{\epsilon_0}{2} \vec{E}_0^2$$

Radiation pressure P on a surface of area A :

$$P = 2 \frac{\langle S \rangle}{c} A \cos^2 \theta \text{ (reflection at incident angle } \theta \text{ relative to normal)}$$

$$P = \frac{\langle S \rangle}{c} A \cos \theta \text{ (absorption)}$$